

MIC38C42A/43A/44A/45A

BiCMOS Current-Mode PWM Controllers

Features

- Fast 40 ns Output Rise and 30 ns Output Fall Times
- -40°C to +85°C Ambient Temperature Range Meets UC284x Specifications
- High-Performance, Low-Power BiCMOS Process
- Ultra-Low Start-Up Current (100 µA Typical)
- Low Quiescent Operating Current (4 mA Typical)
- CMOS Outputs with Rail-to-Rail Swing
- Up to 500 kHz Current-Mode Operation
- Trimmed 5V Bandgap Reference
- Pin-for-Pin Compatible with UC3842/3843/3844/3845
- Trimmed Oscillator Discharge Current
- UVLO with Hysteresis
- Low Cross-Conduction Currents

Applications

- Current-Mode, Offline, Switched-Mode Power Supplies
- Current-Mode, DC-to-DC Converters
- Step-Down Buck Regulators
- Step-Up Boost Regulators
- · Flyback, Isolated Regulators
- · Forward Converters
- Synchronous FET Converters

General Description

The MIC38C4xA fixed-frequency, are high controllers. PWM performance, current-mode Microchip's BiCMOS devices are pin compatible with 384x bipolar devices, but feature several improvements.

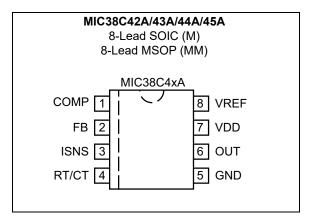
Undervoltage lockout circuitry allows the '42A and '44A versions to start up at 14.5V and operate down to 9V, and the '43A and '45A versions start at 8.4V with operation down to 7.6V. All versions operate up to 20V.

When compared to bipolar 384x devices operating from a 15V supply, start-up current has been reduced to 100 μ A typical and operating current has been reduced to 4.0 mA typical. Decreased output rise and fall times drive larger MOSFETs, and rail-to-rail output capability increases efficiency, especially at lower supply voltages. The MIC38C4xA also features a trimmed oscillator discharge current and bandgap reference.

The MIC38C4xA family is available in 8-pin SOIC and MSOP-8 package options.

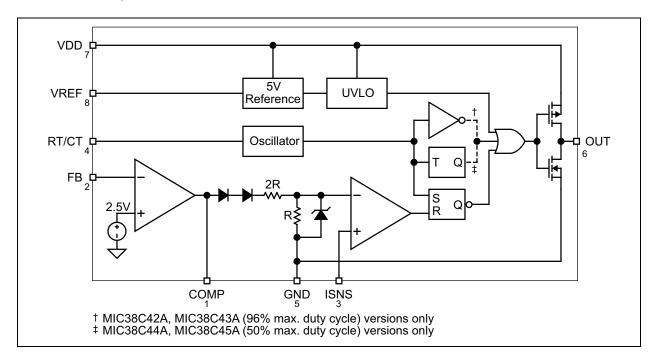
For fast rise and fall times and higher output drive, refer to the MIC38HC4x.

Package Type



MIC38C42A/43A/44A/45A

Functional Diagram



1.0 ELECTRICAL CHARACTERISTICS

Absolute Maximum Ratings †

Supply Voltage (V _{DD})	+20V
Switch Supply Voltage (V _D)	
Current Sense Voltage (V _{ISNS})	
Feedback Voltage (V _{FB})	
Output Current (I _{OUT})	

† Notice: Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operational sections of this specification is not intended. Exposure to maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

Electrical Characteristics: V_{DD} = 15V, Adjust V_{DD} above the start threshold before setting at 15V; R_T = 11.0 kΩ; C_T = 3.3 nF; -40°C ≤ T_A ≤ +85°C; unless noted. Note 1

Parameter	Symbol	Min.	Тур.	Max.	Units	Conditions
Reference						
Output Voltage	V _{REF}	4.90	5.00	5.10	V	T _A = +25°C, I _{VREF} = 1 mA
Line Regulation	$\Delta V_{\text{REF}(\text{LINE})}$		2	20	mV	12V ≤ V _{DD} ≤ 18V, I _{VREF} = 5 μA
Load Regulation	$\Delta V_{REF(LOAD)}$		1	25	mV	1 mA ≤ I _{VREF} ≤ 20 mA
Temperature Stability	TC _{VREF}	_	0.2		mV/°C	Note 2
Total Output Variation	$\Delta V_{REF(TOT)}$	4.82		5.18	V	Line, Load, Temperature, Note 2
Output Noise Voltage	V _{NOISE}	_	50		μV	10 Hz ≤ f ≤ 10 kHz, T _A = +25°C, Note 2
Long-Term Stability	$\Delta V_{REF(LT)}$	—	5	25	mV	T _A = +125°C, 1000 hours, Note 2
Output Short-Circuit	I _{VREF(SC)}	-30	-80	-180	mA	—
Oscillator						
Initial Accuracy	$\Delta f_{OSC(INIT)}$	47	53	59	kHz	T _A = +25°C, Note 3
Voltage Stability	$\Delta f_{OSC(VS)}$	—	0.2	1.0	%	$12V \le V_{DD} \le 18V$
Temperature Stability	TC _{FOSC}	—	0.04		%/°C	$T_{MIN} \le T_A \le T_{MAX}$, Note 2
Clock Ramp Reset Current	I _{DISCHG}	6.0	8.4	9.0	mA	T _A = +25°C, V _{RT/CT} = 2V, Note 2
Amplitude	V _{AMP}		1.9		V _{PP}	V _{RT/CT} peak-to-peak
Error Amp					•	
Input Voltage	V _{IN(EA)}	2.4	2.50	2.58	V	V _{COMP} = 2.5V
Input Bias Current	I _{BIAS(EA)}		-0.1	-2	μA	V _{FB} = 5.0V
Open Loop Voltage Gain	A _{VOL}	65	90	—	dB	$2V \le V_{COMP} \le 4V$
Unity Gain Bandwidth	GBW	0.7	1.0	—	MHz	Note 2
Power Supply Rejection Ratio	PSRR _{EA}	60	_	_	dB	12V ≤ V _{DD} ≤ 18V
Output Sink Current	I _{COMP(SINK)}	2	14	—	mA	V _{FB} = 2.7V, V _{COMP} = 1.1V
Output Source Current	I _{COMP(SRC)}	-0.3	-1	_	mA	V _{FB} = 2.3V, V _{COMP} = 5V
COMP High Voltage	V _{COMP_H}	5	6.8	_	V	V_{FB} = 2.3V, R_{LOAD} = 15 k Ω to ground
COMP Low Voltage	V _{COMP_L}	—	0.1	1.1	V	V_{FB} = 2.7V, R_{LOAD} = 15 k Ω to V_{REF}
Current Sense						
Divider Gain Input-to-Output	A _{DIV}	2.85	3.0	3.15	V/V	Note 4, Note 5
Maximum Threshold	V _{TH(MAX)}	0.9	1	1.1	V	V _{COMP} = 5V, Note 4
Power Supply Rejection Ratio	PSRR _{CS}	_	70	_	dB	12V ≤ V _{DD} ≤ 18V, Note 4
Input Bias Current	I _{BIAS(CS)}	_	-0.1	-2	μA	_
Delay to Output	t _D	_	120	250	ns	
Output						
R _{DS(ON)} Pull High	R _{DSON_H}	_	20		Ω	I _{SOURCE} = 200 mA
R _{DS(ON)} Pull Low	R _{DSON_L}	_	11		Ω	I _{SINK} = 200 mA
Rise Time	t _R	_	40	80	ns	T _A = +25°C, C _{LOAD} = 1 nF
Fall Time	t _F		30	60	ns	T _A = +25°C, C _{LOAD} = 1 nF

ELECTRICAL CHARACTERISTICS (CONTINUED)

Electrical Characteristics: V_{DD} = 15V, Adjust V_{DD} above the start threshold before setting at 15V; R_T = 11.0 kΩ; C_T = 3.3 nF; -40°C ≤ T_A ≤ +85°C; unless noted. Note 1

Parameter	Symbol	Min.	Тур.	Max.	Units	Conditions		
Undervoltage Lockout								
Otant Thus shald	V	13.5	14.5	15.5	V	MIC38C42A/4A		
Start Threshold	V _{TH(ST)}	7.8	8.4	9.0	V	MIC38C43A/5A		
Minimum Operating	V	8	9	10	V	MIC38C42A/4A		
Voltage	V _{DD(MIN)}	7.0	7.6	8.2	V	MIC38C43A/5A		
Pulse Width Modulator								
Maximum Duty Cycle	D _{MAX}	94	96	_	%	MIC38C42A/3A		
		46	50		%	MIC38C44A/5A		
Minimum Duty Cycle	D _{MIN}	—	—	0	%	—		
Total Standby Current								
Start-Up Current	I _{DD(START)}	_	100	230		V _{DD} = 13V for MIC38C42A/44A		
Stan-Op Current				230	μA	V _{DD} = 7.5V for MIC38C43A/45A		
Operating Supply Current	I _{DD(Q)}	_	4.0	6.0	mA	V _{FB} = V _{ISNS} = 0V		

Note 1: Specification for packaged product only.

2: These parameters, although guaranteed, are not 100% tested in production.

3: Output frequency equals oscillator frequency for the MIC38C42A and MIC38C43A. Output frequency for the MIC38C44A and MIC38C45A equals one-half the oscillator frequency.

- 4: Parameter measured at trip point of latch with V_{FB} = 0V.
- **5:** Gain defined as Equation 1-1; $0V \le V_{TH(ISNS)} \le 0.8V$.

EQUATION 1-1:

 $A_{DIV} = \frac{\Delta V_{COMP}}{\Delta V_{TH(ISNS)}}$

TEMPERATURE SPECIFICATIONS (Note 1)

Parameters	Sym.	Min.	Тур.	Max.	Units	Conditions	
Temperature Ranges							
Storage Temperature Range	Τ _S	-65	—	+150	°C	—	
Operating Ambient Temperature Range	Τ _Α	-40	_	+85	°C	—	
Operating Junction Temperature Range	Т _Ј	-40	_	+125	°C	—	
Maximum Junction Temperature	T _{J(MAX)}	_	_	+150	°C	—	
Package Thermal Resistance							
Thermal Resistance MSOP-8	θ _{JA}	—	250	_	°C/W	—	
Thermal Resistance SOIC-8	θ_{JA}	_	170	—	°C/W	—	

Note 1: The maximum allowable power dissipation is a function of ambient temperature, the maximum allowable junction temperature and the thermal resistance from junction to air (i.e., T_A, T_J, θ_{JA}). Exceeding the maximum allowable power dissipation will cause the device operating junction temperature to exceed the maximum +125°C rating. Sustained junction temperatures above +125°C can impact the device reliability.

2.0 TYPICAL PERFORMANCE CURVES

Note: The graphs and tables provided following this note are a statistical summary based on a limited number of samples and are provided for informational purposes only. The performance characteristics listed herein are not tested or guaranteed. In some graphs or tables, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore outside the warranted range.

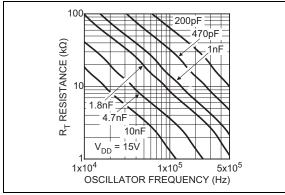
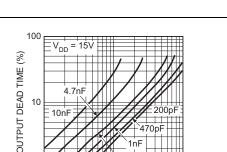


FIGURE 2-1: Configuration.



Oscillator Frequency

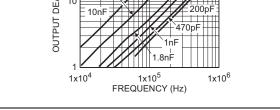


FIGURE 2-2: MIC38C42A/43A Output Dead Time vs. Oscillator Frequency.

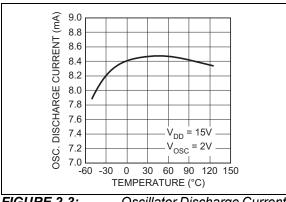


FIGURE 2-3: Oscillator Discharge Current vs. Temperature.

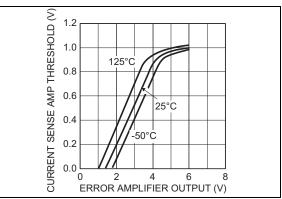


FIGURE 2-4: Current Sense Amplifier Threshold vs. Error Amplifier Output.

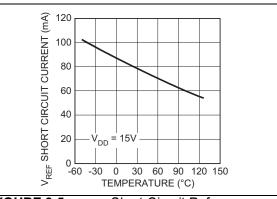
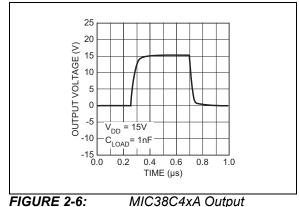


FIGURE 2-5: Short-Circuit Reference Current vs. Temperature.



Waveform.

3.0 PIN DESCRIPTIONS

The descriptions of the pins are listed in Table 3-1.

TABLE 3-1:PIN FUNCTION TABLE

Pin Number	Pin Name	Description
1	COMP	Compensation: Connect external compensation network to modify the error amplifier output.
2	FB	Feedback (Input): Error amplifier input. Feedback is 2.5V at desired output voltage.
3	ISNS	Current Sense (Input): Current sense comparator input. Connect to current sensing resistor or current transformer.
4	RT/CT	Timing Resistor/Timing Capacitor: Connect external RC network to select switching frequency.
5	GND	Ground: Combined analog and power ground.
6	OUT	Gate Driver Output: Totem-pole output.
7	VDD	Analog Supply (Input): Controller circuitry supply input. Return to analog ground (GND).
8	VREF	5V Reference (Output): Connect external RC network.

4.0 FUNCTIONAL DESCRIPTION

Familiarity with 384x converter designs is assumed.

4.1 MIC38C4xA Advantages

4.1.1 START-UP CURRENT

Start-up current has been reduced to an ultra-low $100 \ \mu A$ (typical) permitting higher-resistance, lower-wattage, start-up resistors (powers controller during power supply start-up). The reduced resistor wattage reduces cost and printed circuit space.

4.1.2 OPERATING CURRENT

Quiescent operating current has been reduced to 4 mA compared to 11 mA for a typical bipolar controller. The controller runs cooler and the V_{DD} hold-up capacitance required during start-up may be reduced.

4.1.3 OUTPUT DRIVER

Complementary internal P-channel and N-channel MOSFETs produce rail-to-rail output voltages for better performance driving external power MOSFETs. The driver transistor's low on resistance and high peak current capability can drive gate capacitances of greater than 1000 pF. The value of output capacitance which can be driven is determined only by the rise/fall time requirements. Within the restrictions of output capacity and controller power dissipation, maximum switching frequency can approach 500 kHz.

4.2 Design Precautions

When operating near 20V, circuit transients can easily exceed the 20V absolute maximum rating, permanently damaging the controller's CMOS construction. To reduce transients, connect a 0.1 μ F low-ESR capacitor to next to the controller's supply V_{DD} and ground connections. Film type capacitors, such as Wima MKS2, are recommended.

When designing high-frequency converters, avoid capacitive and inductive coupling of the switching waveform into high impedance circuitry such as the error amplifier, oscillator, and current sense amplifier. Avoid long printed-circuit traces and component leads. Locate oscillator and compensation circuitry near the IC. Use high frequency decoupling capacitors on V_{REF} , and if necessary, on V_{DD} . Return high di/dt currents directly to their source and use large area ground planes.

4.3 Buck Converter

Refer to Figure 4-1. When at least 26V is applied to the input, C5 is charged through R2 until the voltage V_{DD} is greater than 14.5V (the undervoltage lockout value of the MIC38C42A). Output switching begins when Q1 is

turned on by the gate drive transformer T1, charging the output filter capacitor C3 through L1. D5 supplies a regulated +12V to V_{DD} once the circuit is running.

Current sense transformer CT1 provides current feedback to ISNS for current-mode operation and cycle-by-cycle current limiting. This is more efficient than a high-power sense resistor and provides the required ground-referenced level shift.

When Q1 turns off, current flow continues from ground through D1 and L1 until Q1 is turned on again.

The 100V Schottky diode D1 reduces the forward voltage drop in the main current path, resulting in higher efficiency than could be accomplished using an ultra-fast-recovery diode. R1 and C2 suppress parasitic oscillations from D1.

Using a high-value inductance for L1 and a low-ESR capacitor for C3 permits small capacitance with minimum output ripple. This inductance value also improves circuit efficiency by reducing the flux swing in L1.

Magnetic components are carefully chosen for minimal loss at 500 kHz. CT1 and T1 are wound on Magnetics, Inc. P-type material toroids. L1 is wound on a Siemens N49 EFD core.

TABLE 4-1:	MAGNETIC COMPONENTS
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Symbol	Custom Coils (Note 1)	ETS (Note 2)
CT1	4923	ETS 92420
T1	4924	ETS 92419
L1	4925	ETS 92421

Note 1: Custom Coils, Alcester, SD. Tel: (605) 934-2460.

2: Energy Transformation Systems, Inc. Tel: (510) 656-2012.

 TABLE 4-2:
 COMPONENT TEST RESULTS

Test	Conditions	Results
Line Regulation	V _{IN} = 26V to 80V, V _{OUT} = 12V, I _O = 2A	0.5%
Load Regulation	$V_{IN} = 48V, V_{OUT} = 12V, I_{O} = 0.2A \text{ to } 2A$	0.6%
Efficiency	V _{IN} = 48V, V _{OUT} = 12V, I _O = 2A	90%
Output Ripple	V _{IN} = 48V, V _{OUT} = 12V, I _O = 2A (20 MHz BW)	100 mV

MIC38C42A/43A/44A/45A

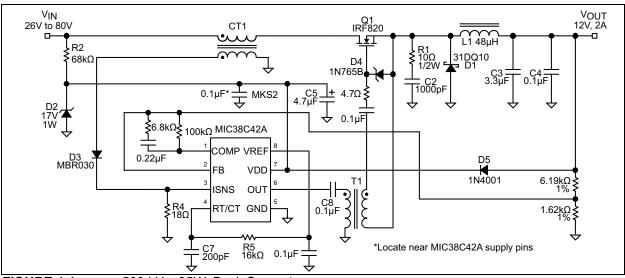


FIGURE 4-1: 500 kHz, 25W, Buck Converter.

4.4 Synchronous Buck Converter

Refer to Figure 4-2. This MIC38C43A synchronous buck converter uses an MIC5022 half-bridge driver to alternately drive the PWM switch MOSFET (driven by GATEH, or high-side output) and a MOSFET which functions as a synchronous rectifier (driven by the GATEL, or low-side output).

The low-side MOSFET turns on when the high-side MOSFET is off, allowing current to return from ground. Current flows through the low-side MOSFET in the source to drain direction.

The on-state voltage drop of the low-side MOSFET is lower than the forward voltage drop of an equivalent Schottky rectifier. This lower voltage drop results in higher efficiency.

A sense resistor $(5 \text{ m}\Omega)$ is connected to the driver's high-side current sense inputs to provide overcurrent protection. Refer to the MIC5020, MIC5021, and MIC5022 data sheets for more information.

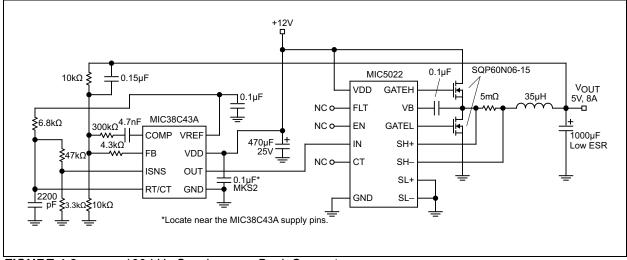
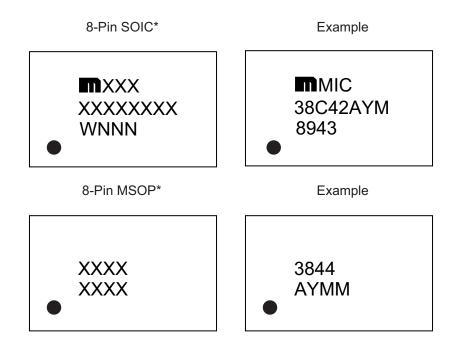


FIGURE 4-2:

100 kHz Synchronous Buck Converter.

5.0 PACKAGING INFORMATION

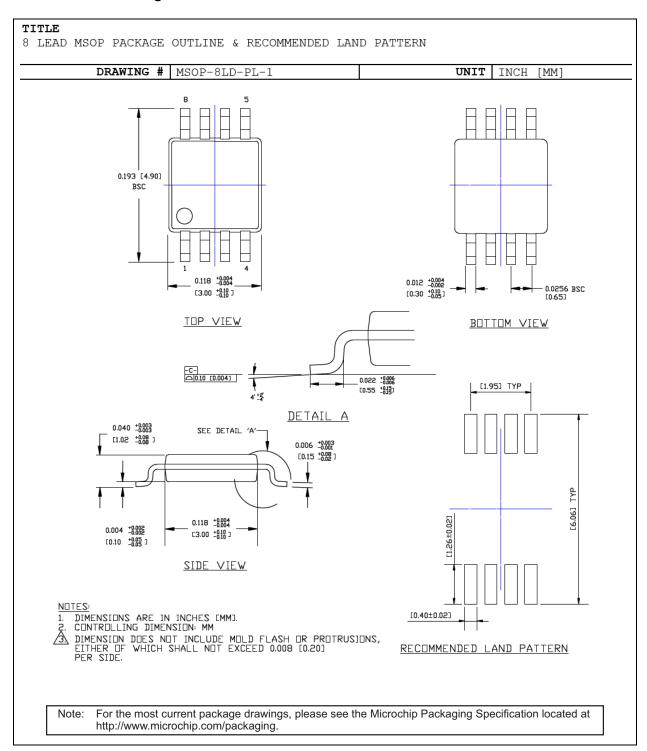
5.1 Package Marking Information



Legend	: XXX Y YY WW NNN (€3) * •, ▲, ▼ mark).	Product code or customer-specific information Year code (last digit of calendar year) Year code (last 2 digits of calendar year) Week code (week of January 1 is week '01') Alphanumeric traceability code Pb-free JEDEC [®] designator for Matte Tin (Sn) This package is Pb-free. The Pb-free JEDEC designator ((e3)) can be found on the outer packaging for this package.
	be carried characters the corpor	.
	Underbar	(_) and/or Overbar (⁻) symbol may not be to scale.

TITLE 8 LEAD SOICN PACKAGE OUTLINE & RECOMMENDED LAND PATTERN DRAWING # SOICN-8LD-PL-1 UNIT INCH [MM] BOTTOM MARK 0.085-0.100 DIA PIN #1 ID MARK 0.236±0.008 [5.99±0.21] F 0.016 +0.0032 -0.0022 [0.41 +0.08] 0.1.94 +0.002 [4.93 +0.05] 0.050[1.27] BSC BOTTOM VIEW TOP VIEW -C-0.004[0.10] 0.025 +0.025 5' +3° [0.64 +0.63] 0.013 +0.007 -0.003 ×45 [0.33 +0.17 -0.08] SEE DETAIL 'A' DETAIL "A" 0.064^{+0.004} [1.63^{+0.10} [1.63^{+0.10} [5.50 +0.05] 0.008 +0.0018 -0.0005 [0.20 +0.05 -0.01] 0.155 +0.002 0.006 +0.004 [3.94 +0.05] A [0.15 +0.10] [2,20 +0.05] END VIEW [0.70 ±0.05]— NDTES [1.27 BSC] DIMENSIONS ARE IN INCHESEMM]. CONTROLLING DIMENSION: INCHES. 1.2. DIMENSION DOES NOT INCLUDE MOLD FLASH OR PROTRUSIONS, EITHER OF WHICH SHALL NOT EXCEED 0.010[0.25] RECOMMENDED LAND PATTERN PER SIDE. Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging.

8-Lead SOIC Package Outline and Recommended Land Pattern



8-Lead MSOP Package Outline and Recommended Land Pattern

NOTES:

APPENDIX A: REVISION HISTORY

Revision A (October 2020)

- Converted Micrel document MIC38C42A/43A/ 44A/45A to Microchip data sheet DS20006437A.
- Minor text changes throughout.

NOTES:

PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, contact your local Microchip representative or sales office.

Device	x	XX	[- <u>XX]</u>	Examples:	
Part No.	∆ Temp. Range	AA Package	[-∆∆] Media Type	a) MIC38C42	A: BiCMOS Current-Mode PWN Controller, 96% Max. Duty Cycle, UVLO Threshold Star 14.5V, Min. Operating 9V, –40
Device:	(Se Spe MIC38C42A: 96% Star	e Selection Gui cific Detail) 6 Max. Duty Cy tup 14.5V, Min.		MIC38C42AYM MIC38C42AYM MIC38C42AYM MIC38C42AYM MIC38C42AYM	to +125°C Junction Temperat Range I: 8-Lead SOIC, 95/Tube I-TR: 8-Lead SOIC, 2,500/Reel IM: 8-Lead MSOP, 100/Tube
	Star MIC38C44A: 50% Star Star MIC38C45A: 50%	tup 8.4V, Min. (6 Max. Duty Cy tup 14.5V, Min. 6 Max. Duty Cy	cle, UVLO Threshold Operating 7.6V cle, UVLO Threshold . Operating 9V cle, UVLO Threshold Operating 7.6V	b) MIC38C43	
Junction Temperature Range:	$Y = -40^{\circ}C \text{ to } $	+125°C, RoHS-	Compliant	MIC38C43AYM MIC38C43AYM MIC38C43AYM MIC38C43AYM	8-Lead SOIC, 95/Tube I-TR: 8-Lead SOIC, 2,500/Reel IM: 8-Lead MSOP, 100/Tube
Package: M = 8-Lead SOIC MM = 8-Lead MSOP Media Type: TR = 2,500/Reel (blank)= 95/Tube for M Package (blank)= 100/Tube for MM Package			3	c) MIC38C44 MIC38C44AYM MIC38C44AYM MIC38C44AYM	Controller, 50% Max. Duty Cycle, UVLO Threshold Star 14.5V, Min. Operating 9V, -40 to +125°C Junction Temperat Range I: 8-Lead SOIC, 95/Tube I-TR: 8-Lead SOIC, 2,500/Reel
Selection G	uide			MIC38C44AYM d) MIC38C45	IM-TR: 8-Lead MSOP, 2,500/Reel
Duty Cycle	U	IVLO Thres	holds		8.4V, Min. Operating 7.6V, -40°C to +125°C Junction
	Start-Up 8 Min. Operatin		Start-Up 14.5V Min. Operating 9V	MIC38C45AYM MIC38C45AYM	Temperature Range I: 8-Lead SOIC, 95/Tube
0% to 96%	MIC38C4	3A	MIC38C42A	MIC38C45AYM	
0% to 50%	MIC38C4	5A	MIC38C44A	MIC38C45AYM	IM-TR: 8-Lead MSOP, 2,500/Reel
				cata use the Sale	e and Reel identifier only appears in the alog part number description. This identifier i d for ordering purposes and is not printed or device package. Check with your Microchip es Office for package availability with the e and Reel option.

NOTES:

Note the following details of the code protection feature on Microchip devices:

- · Microchip products meet the specifications contained in their particular Microchip Data Sheet.
- Microchip believes that its family of products is secure when used in the intended manner and under normal conditions.
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